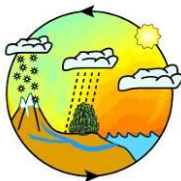


Isotopic Assessment of Animal Origin

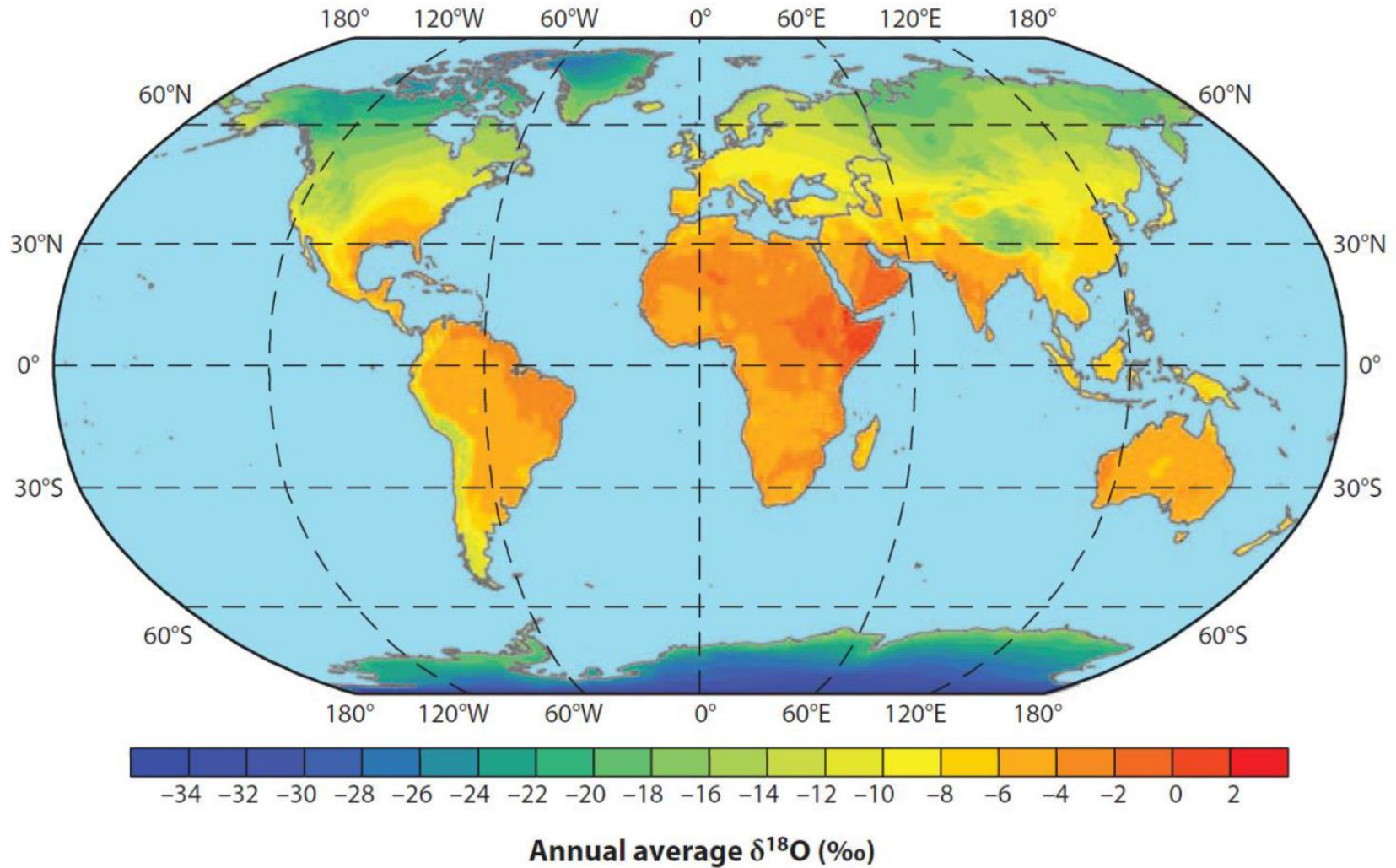
Gabe Bowen
gabe.bowen@utah.edu



Migratory Origin Questions

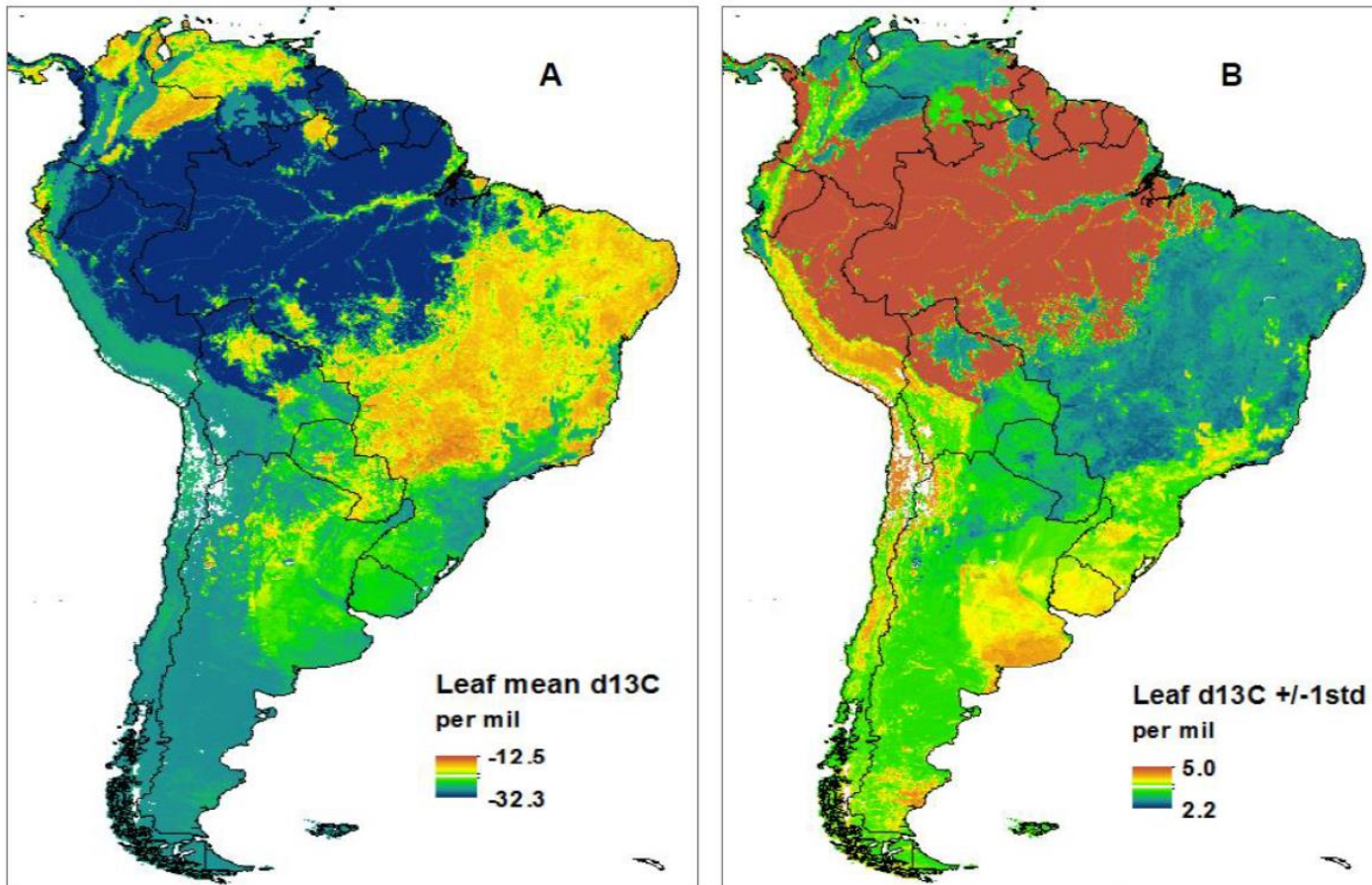
- ⊕ Where did this individual breed?
- ⊕ Where did this individual NOT breed?
- ⊕ Which country did this individual come from?
- ⊕ What is the most likely country of origin?
- ⊕ Is this cheese from Parma?
- ⊕ What is the pattern of pattern of connectivity in this population?

Useful Isotope Systems...



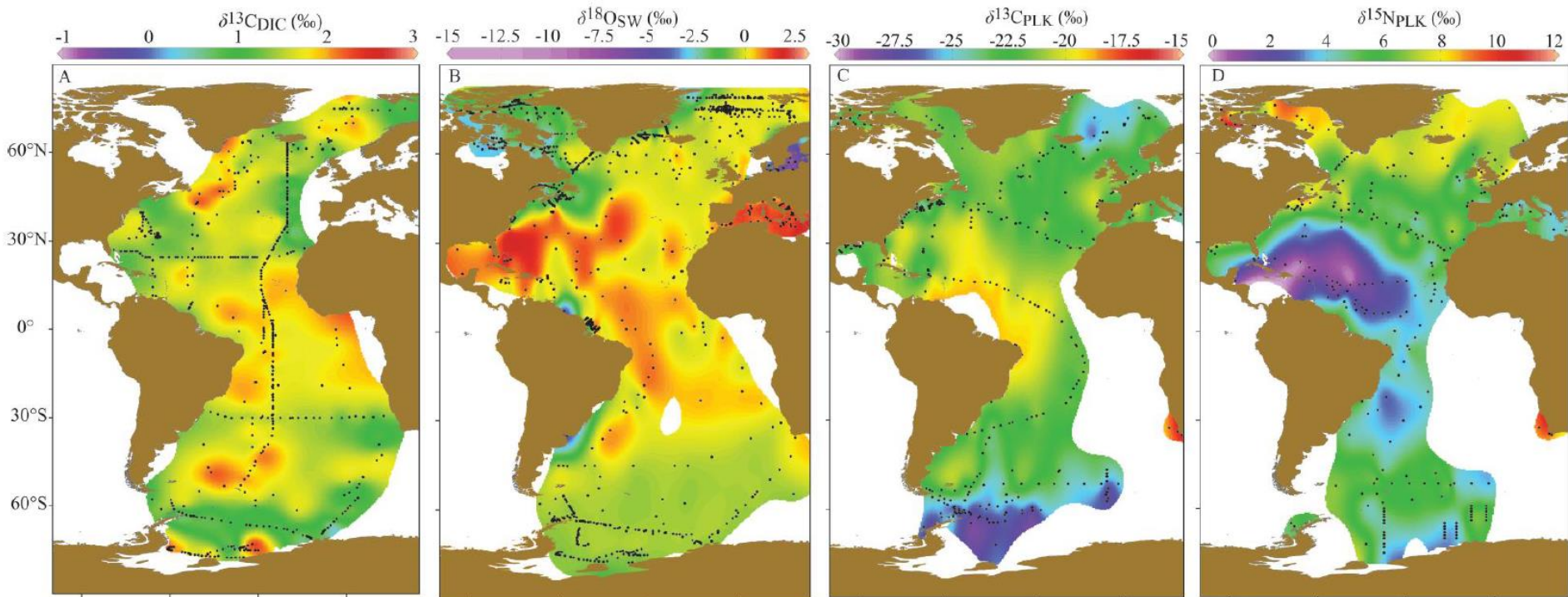
Useful Isotope Systems...

South American canopy leaf $\delta^{13}\text{C}$ predictions

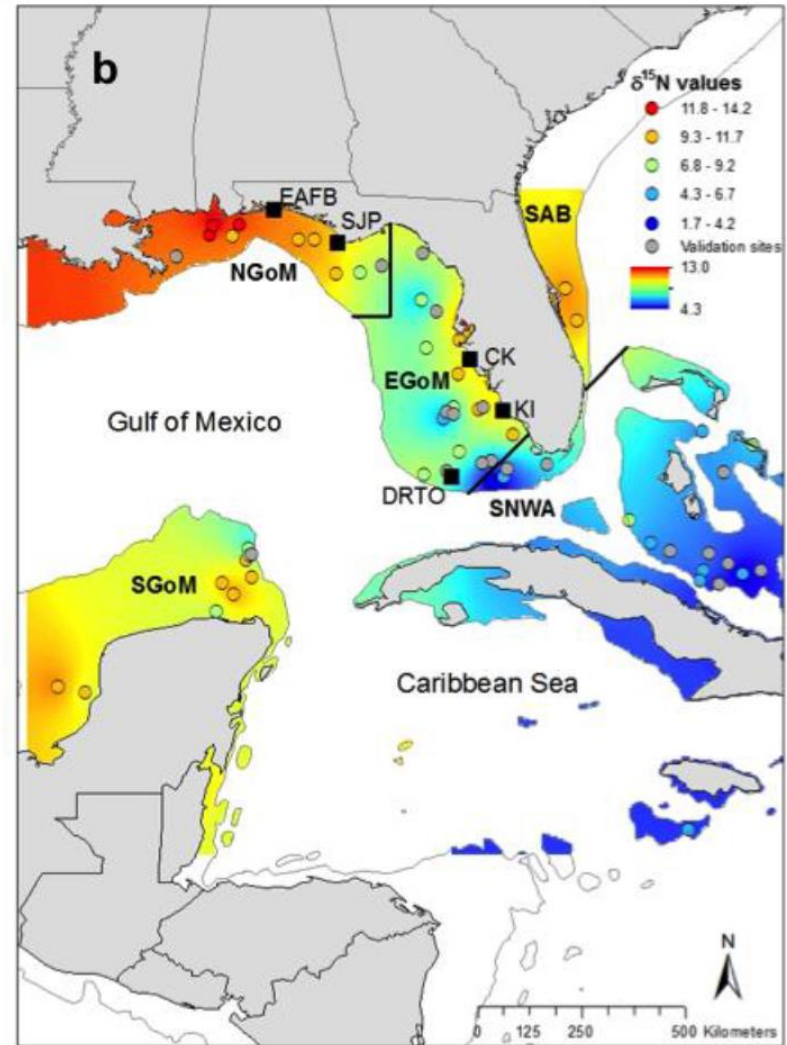
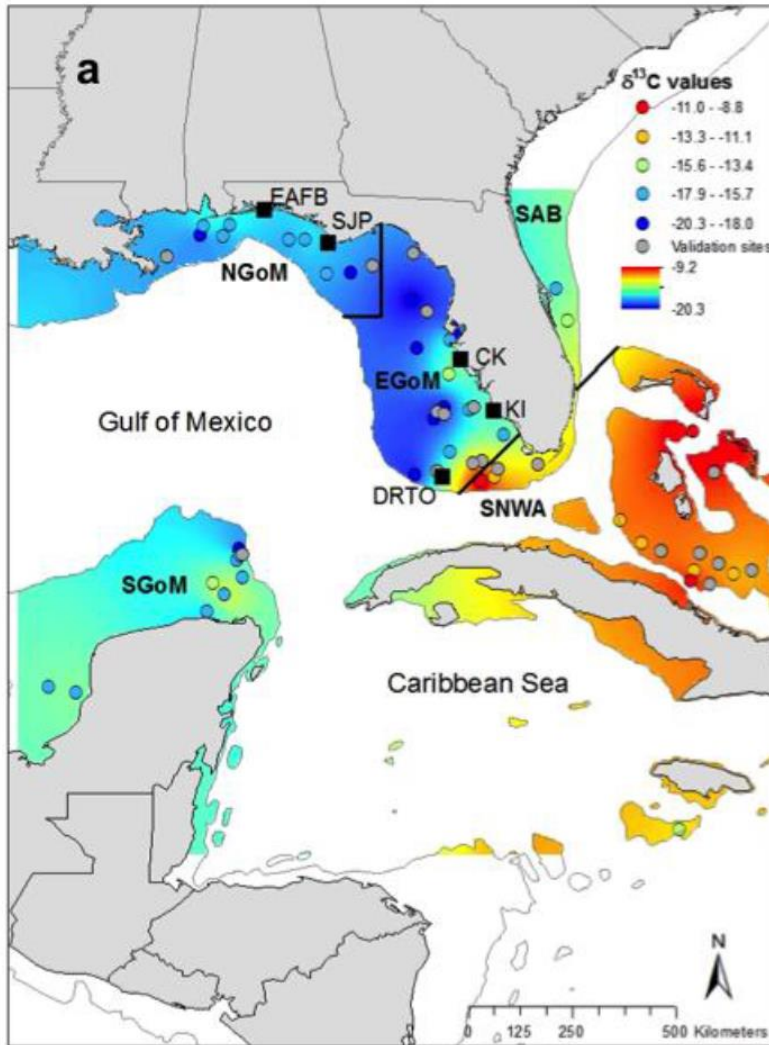


Powell, Yoo, and Still, "Vegetation and Soil Carbon-13 Isoscapes for South America: Integrating Remote Sensing and Ecosystem Isotope Measurements" *Ecosphere* (2012)

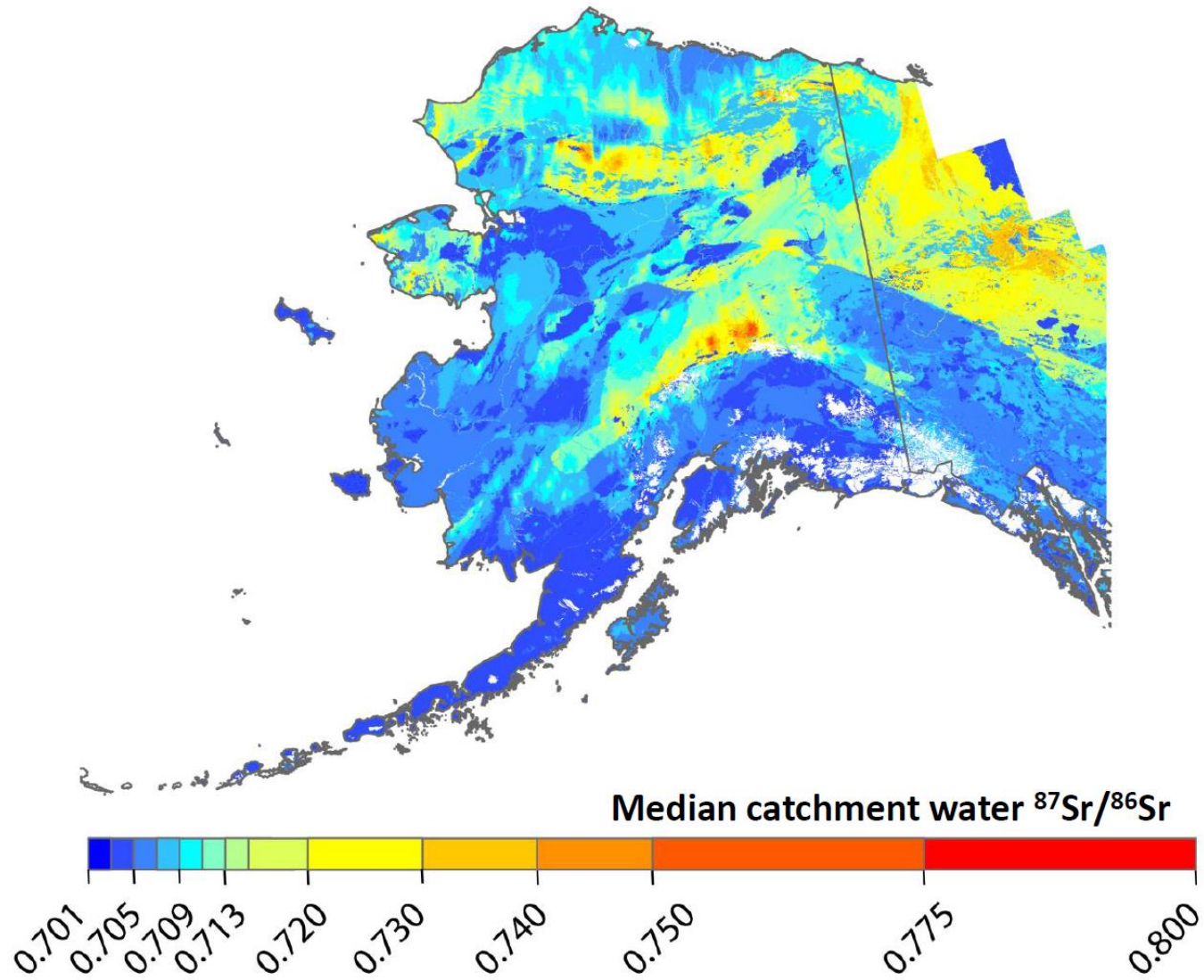
Useful Isotope Systems...



Useful Isotope Systems...



Useful Isotope Systems...



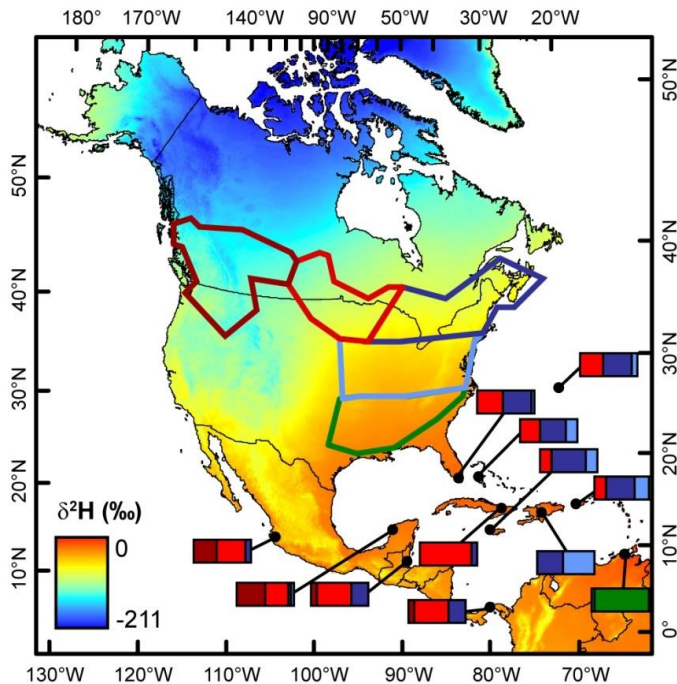
Bayesian Inference of Origin

$$P(A_i|B) = \frac{P(B|A_i)P(A_i)}{\sum P(B|A_j)P(A_j)}$$

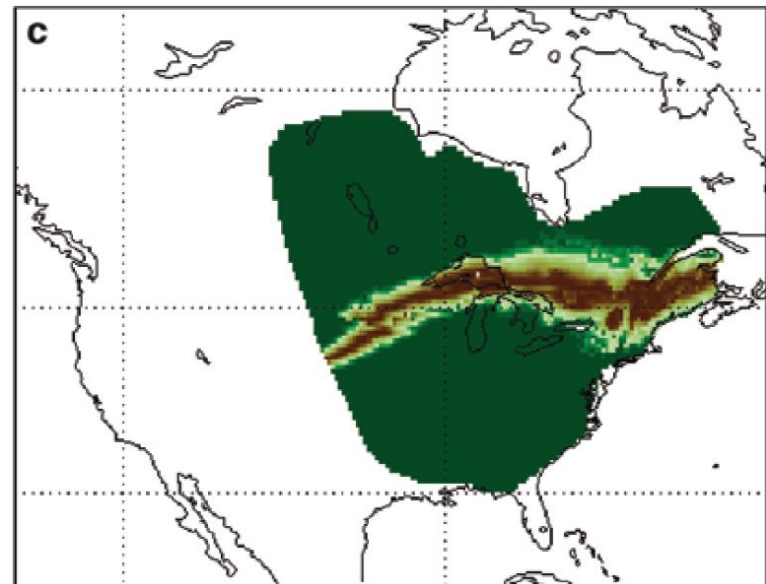
- ⊕ The posterior probability of model i being the true model given some observations is a function of
 - ⊕ The conditional probability of the observations given model i
 - ⊕ The prior probability of model i
 - ⊕ The probabilities associated with all other hypotheses

Defining Hypotheses

⊕ Discrete (nominal)



⊕ Continuous



Defining Hypotheses

⊕ Discrete (nominal)

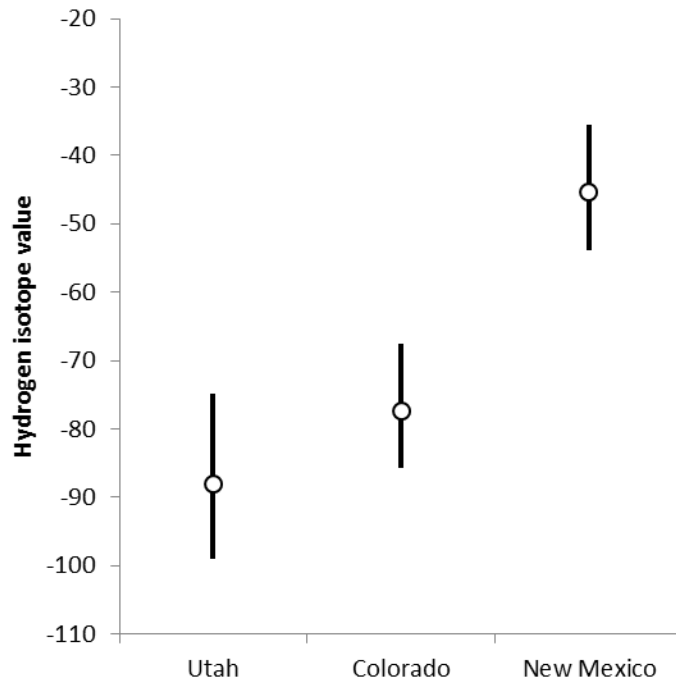
- ⊕ Pose hypotheses in terms of discrete regions from outset
- ⊕ + analysis unit can reflect question (management unit, political boundaries)
- ⊕ + unit structures sampling needed to evaluate conditional probabilities
- ⊕ - units are sometimes ecologically unrealistic
- ⊕ - inflexible (granularity not suited to re-analysis)

⊕ Continuous

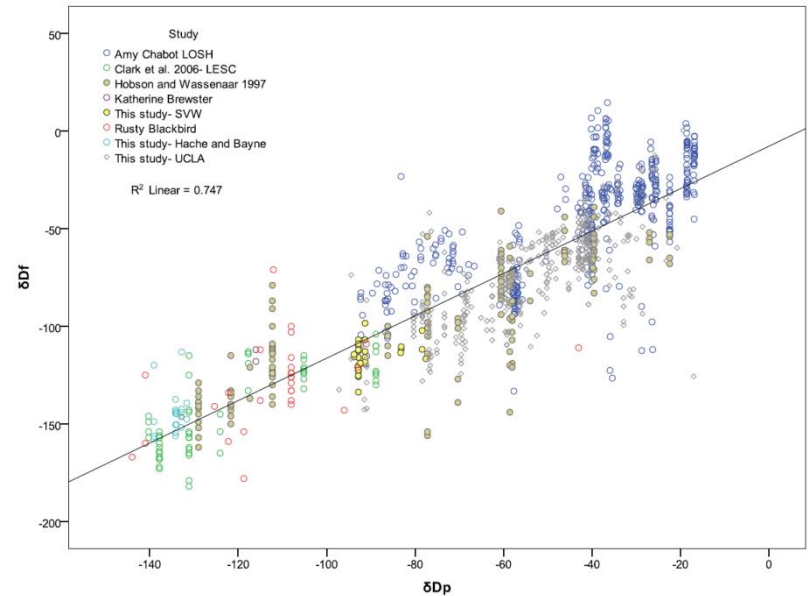
- ⊕ Pose hypotheses in terms of large number of arbitrary (evenly distributed) locations
- ⊕ + preserves maximum information content
- ⊕ + conducive to reanalysis
- ⊕ - requires post-analysis summarization to answer ecological and management questions
- ⊕ - requires model-based evaluation of conditional probabilities

Evaluating Conditional Probabilities

Sample-based



Model-based



Evaluating Conditional Probabilities

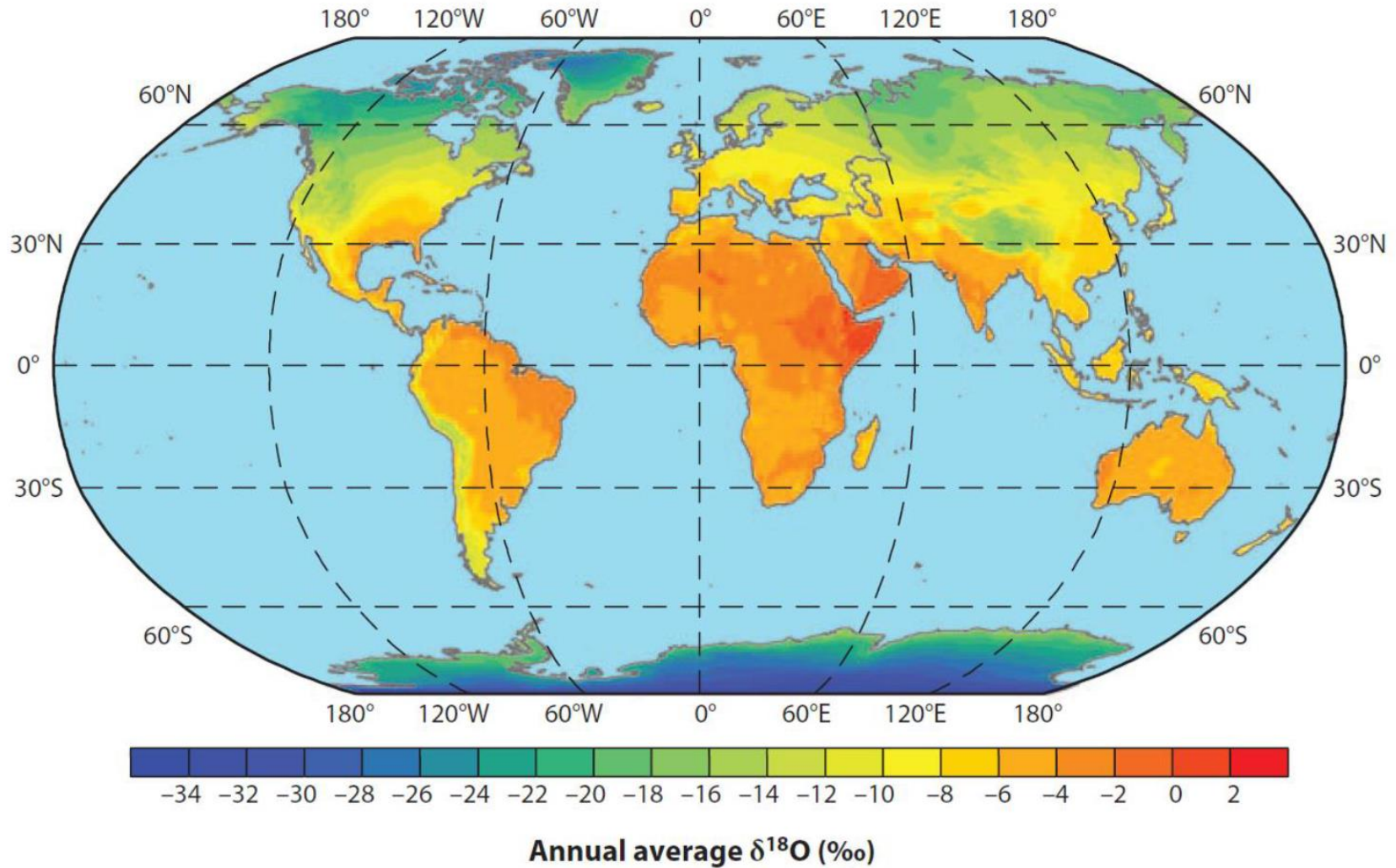
⊕ Sample-based

- ⊕ Sample known-origin individuals to characterize the distribution of values
- ⊕ + simple estimation of distribution
- ⊕ - labor-intensive and expensive
- ⊕ - prohibitive for continuous analysis

⊕ Model-based

- ⊕ Use existing data + information about system to estimate distribution
- ⊕ + cheap
- ⊕ + amenable to continuous analysis
- ⊕ - requires model (for full distribution)
- ⊕ - estimating uncertainty can be challenging and complex

Model-based Starting Point



From Environment to Tissue

You are what you eat...

From Environment to Tissue

**You are what you eat...
+ 3‰**

From Environment to Tissue

You are what you eat...

~~+3‰~~

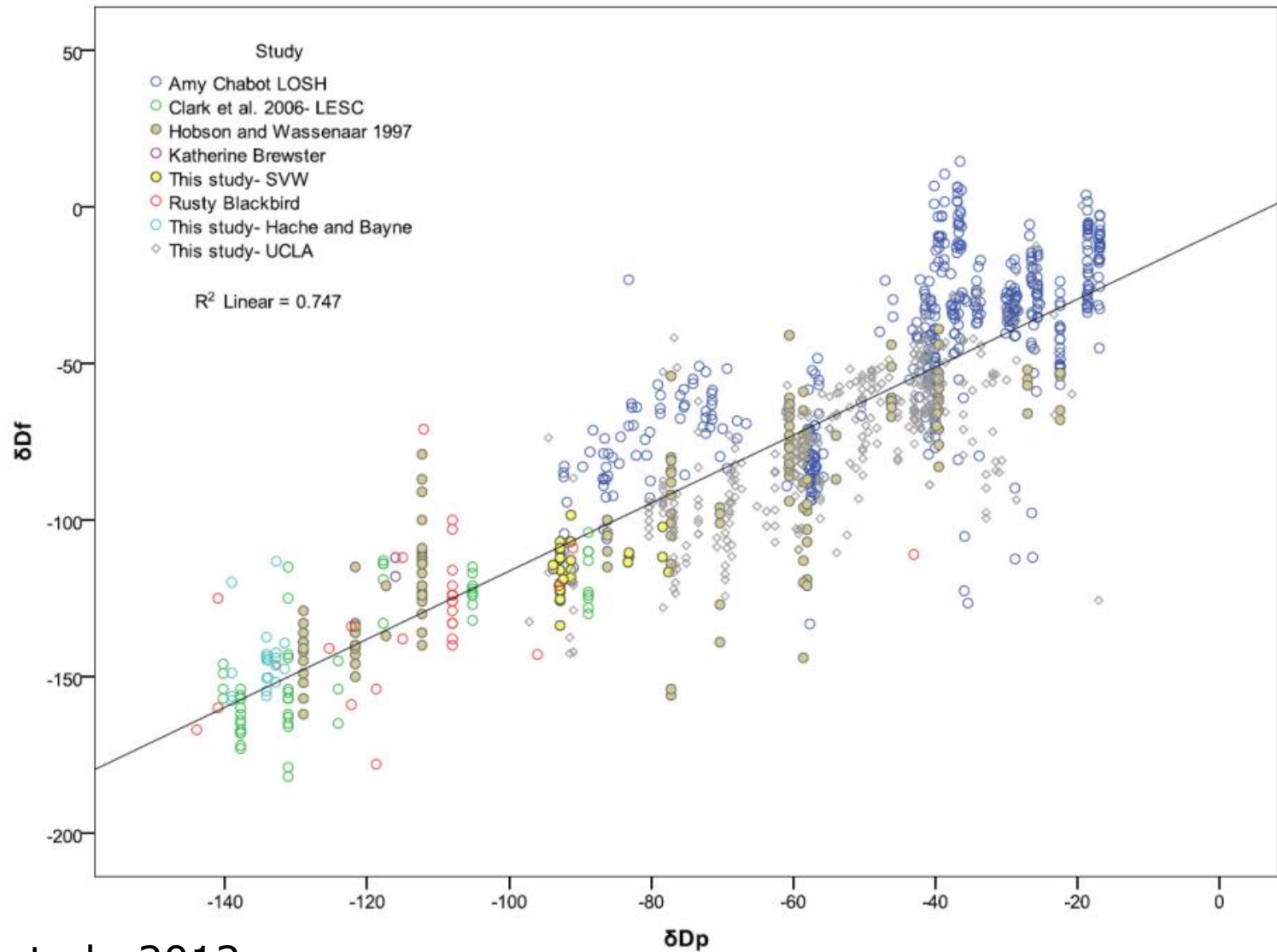
+ what you drink

+ what you breathe

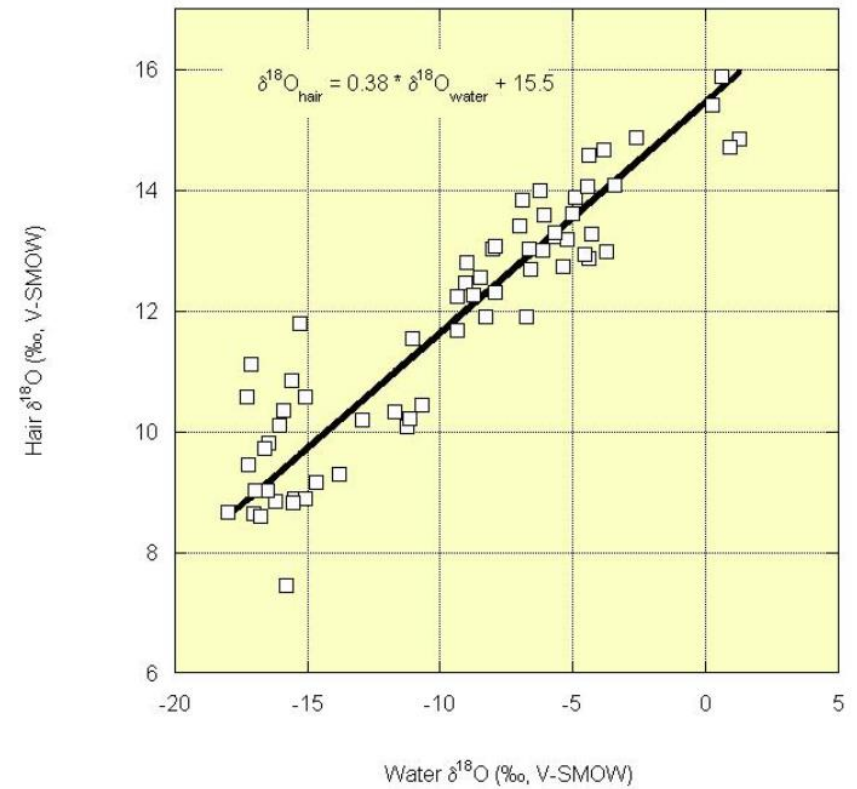
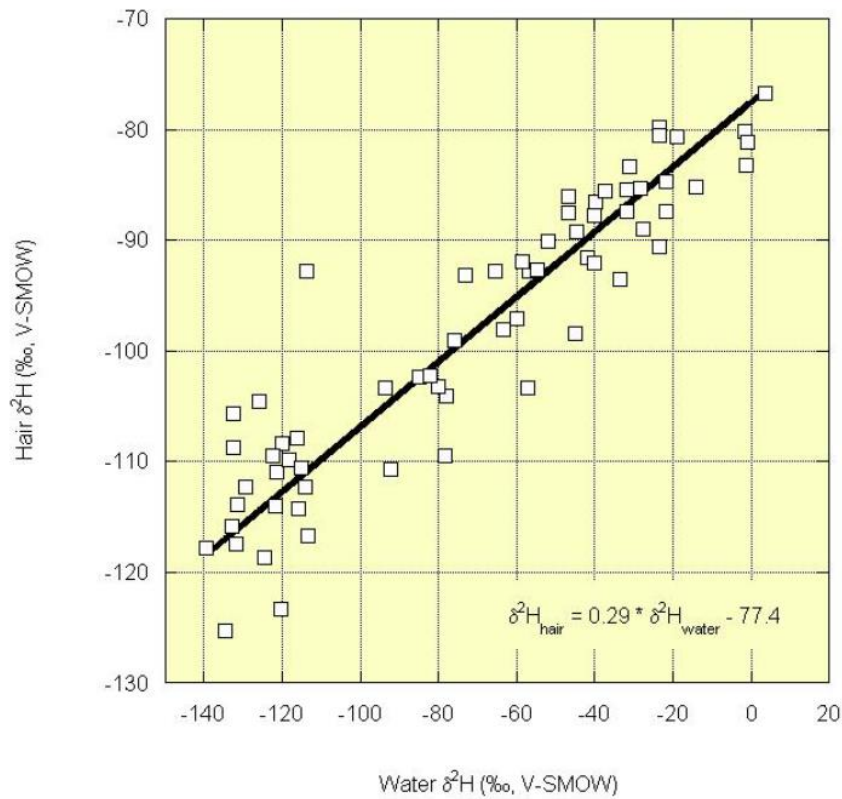
- any fractionating losses

**+/- any fractionation associated with tissue
synthesis**

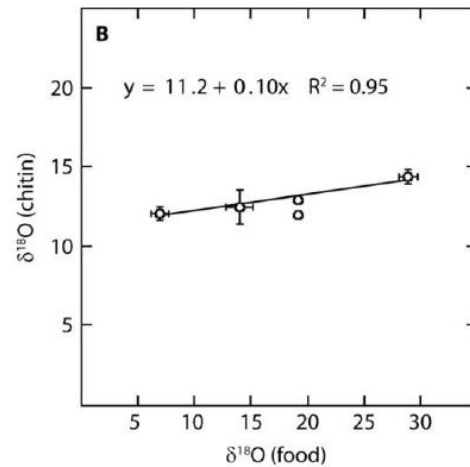
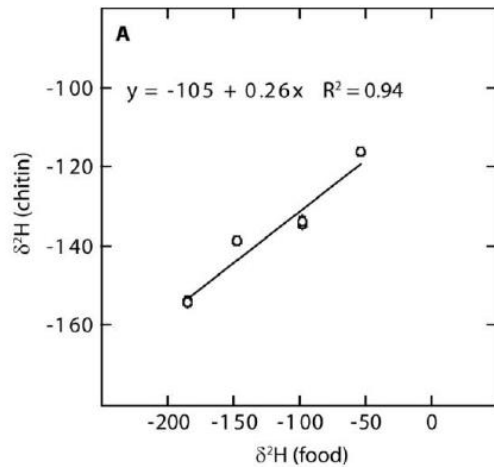
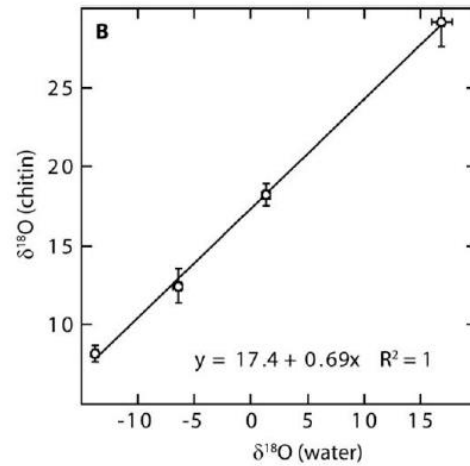
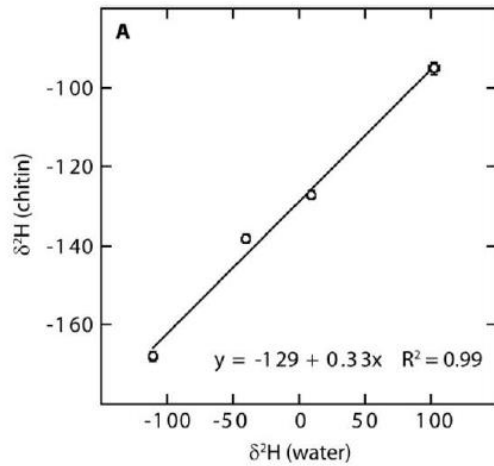
Empirical Calibration



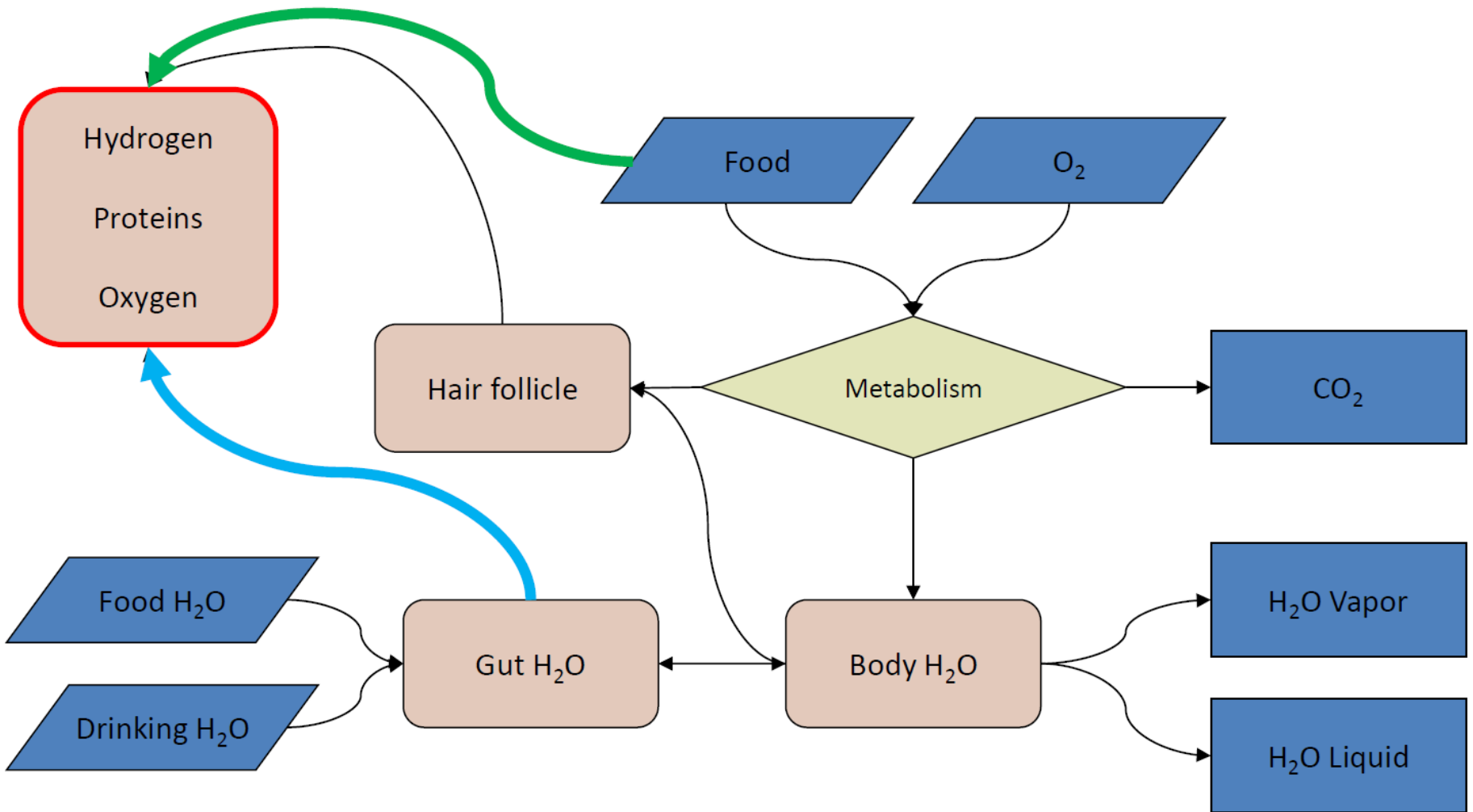
Empirical Calibration



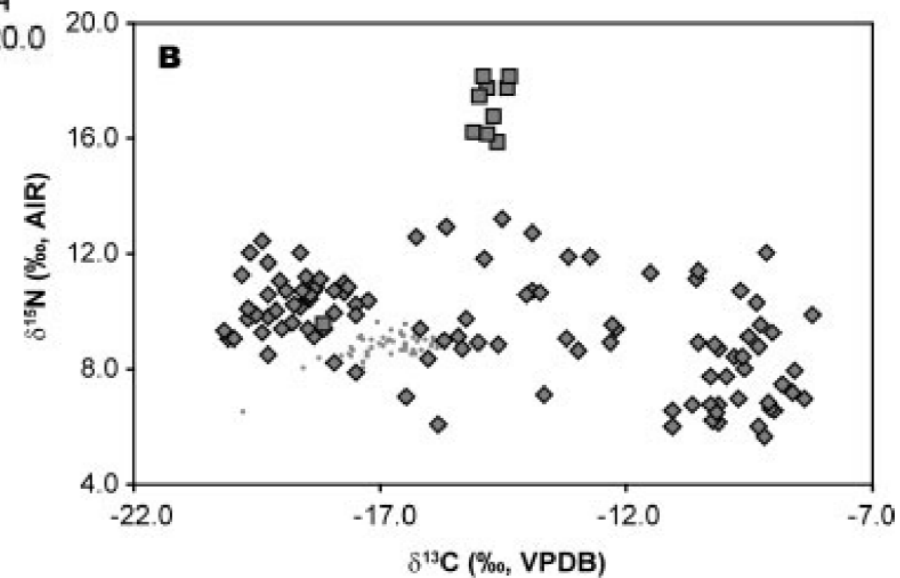
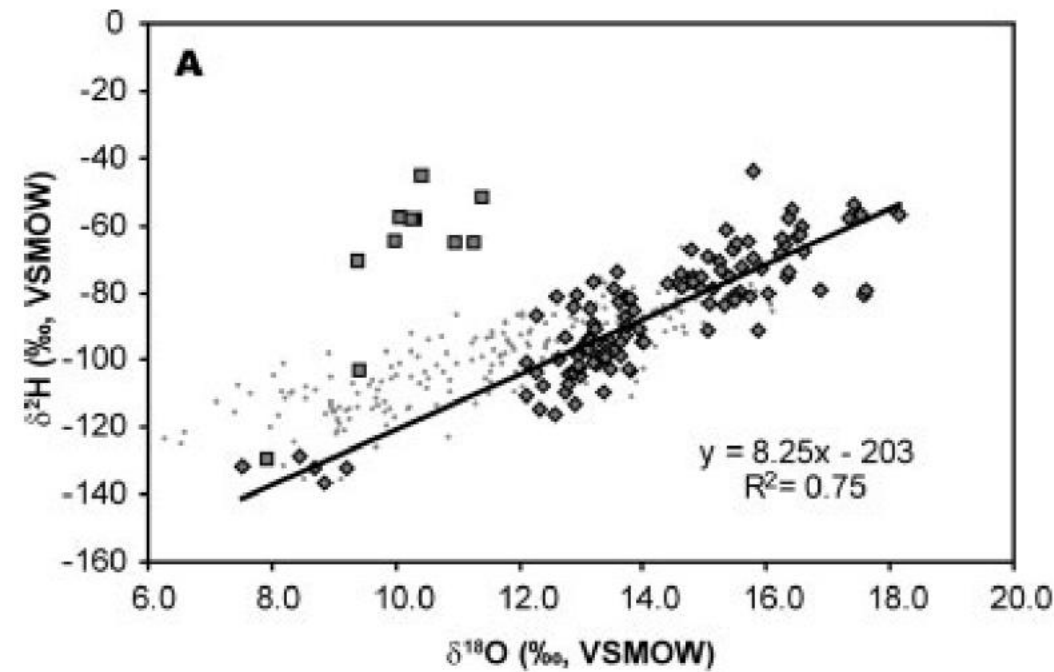
Experimental Calibration



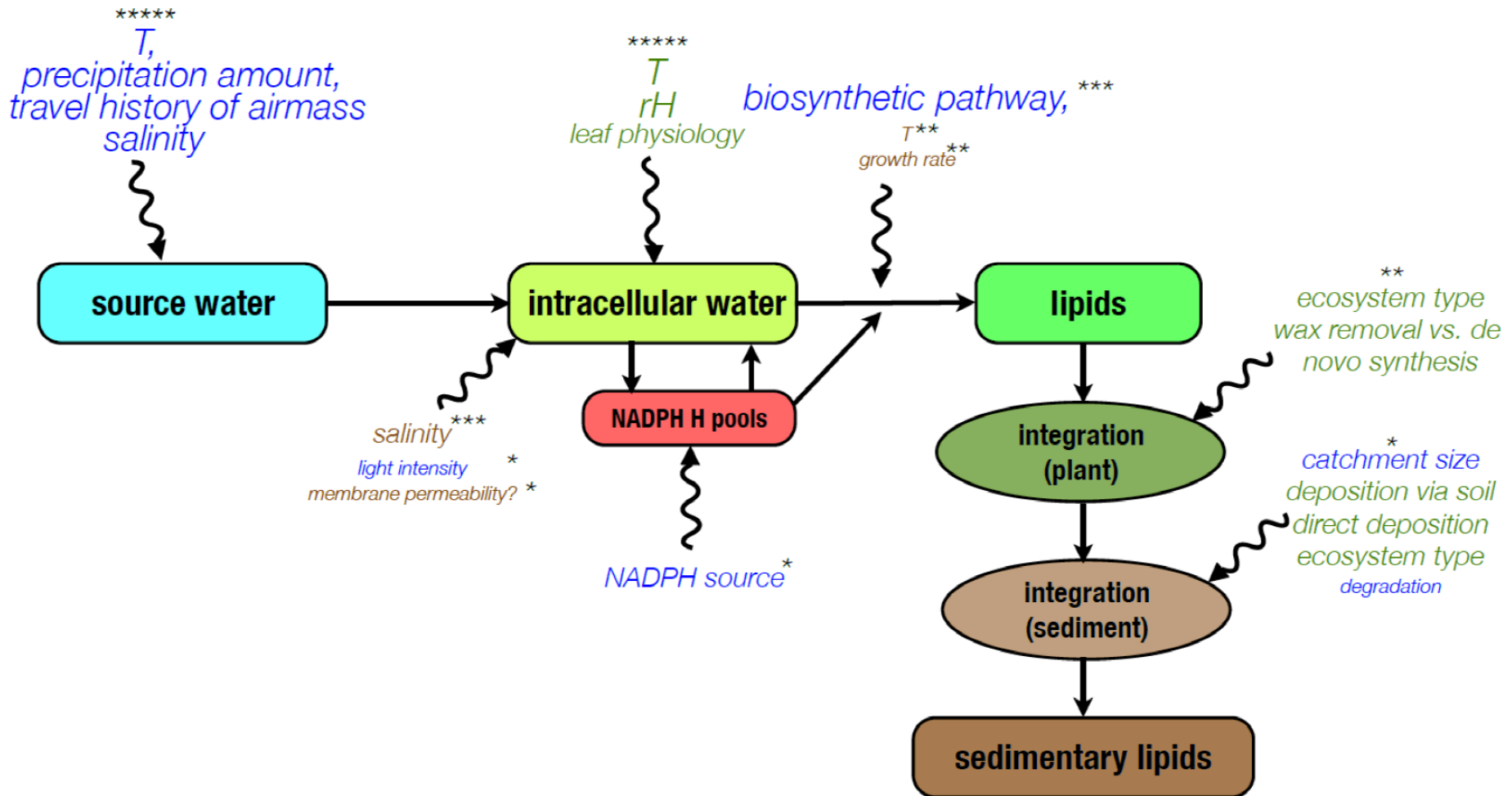
Theoretical Calibration Model



Theoretical Calibration Model



Theoretical Calibration Model

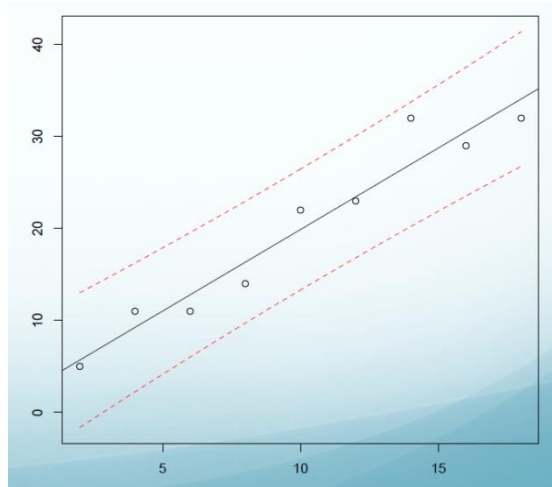


Evaluating Conditional Probabilities: Model Estimates of PDFs

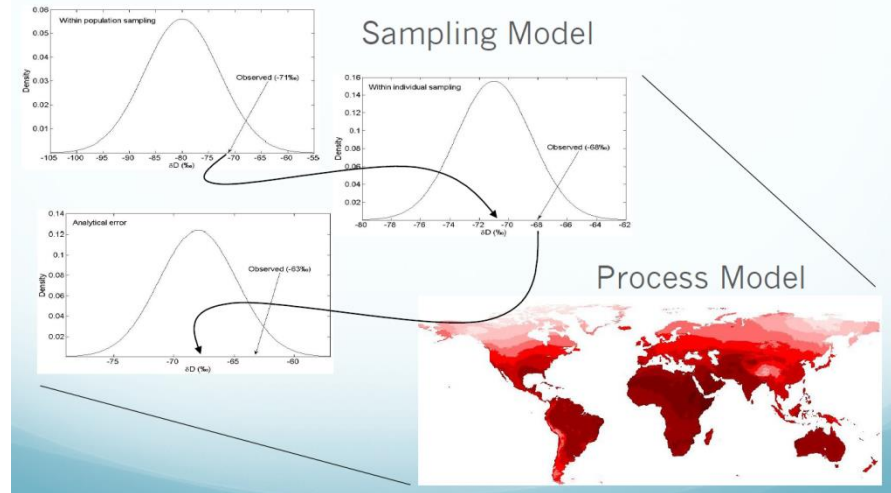
- ⊕ Estimation of mean values expected for each hypothesis is not enough, we must describe the complete probability density function
- ⊕ Sample-based approach allows straight-forward characterization of distribution of expected values associated with a given hypothesis
- ⊕ Estimation of distribution is more challenging with model-based approach
 - ⊕ Challenge grows with complexity of model
 - ⊕ Opportunity to learn grows with complexity of model

Model Estimates of PDFs

⊕ Aggregate estimation



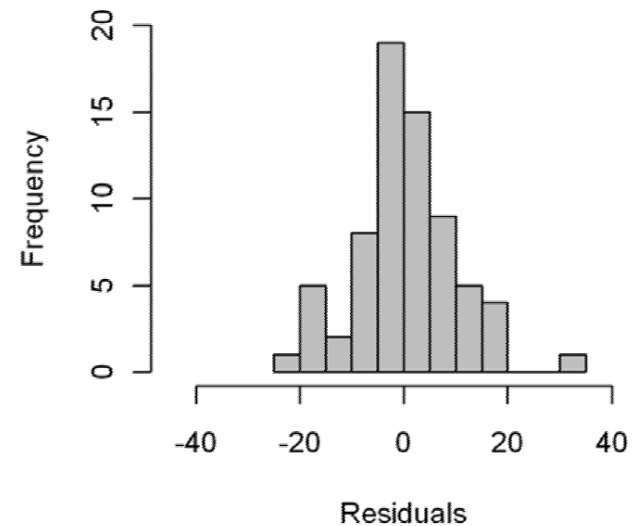
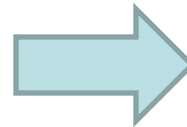
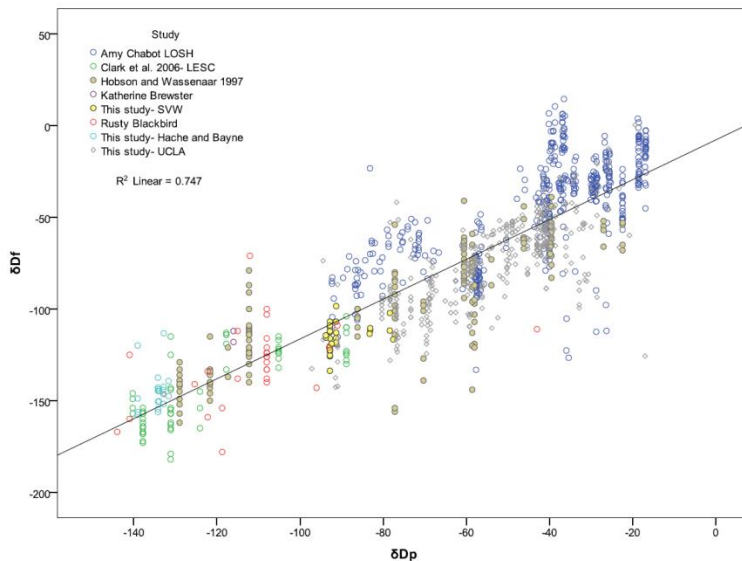
⊕ Hierarchical estimation



*In both cases we are often assuming parametric distributions for simplicity

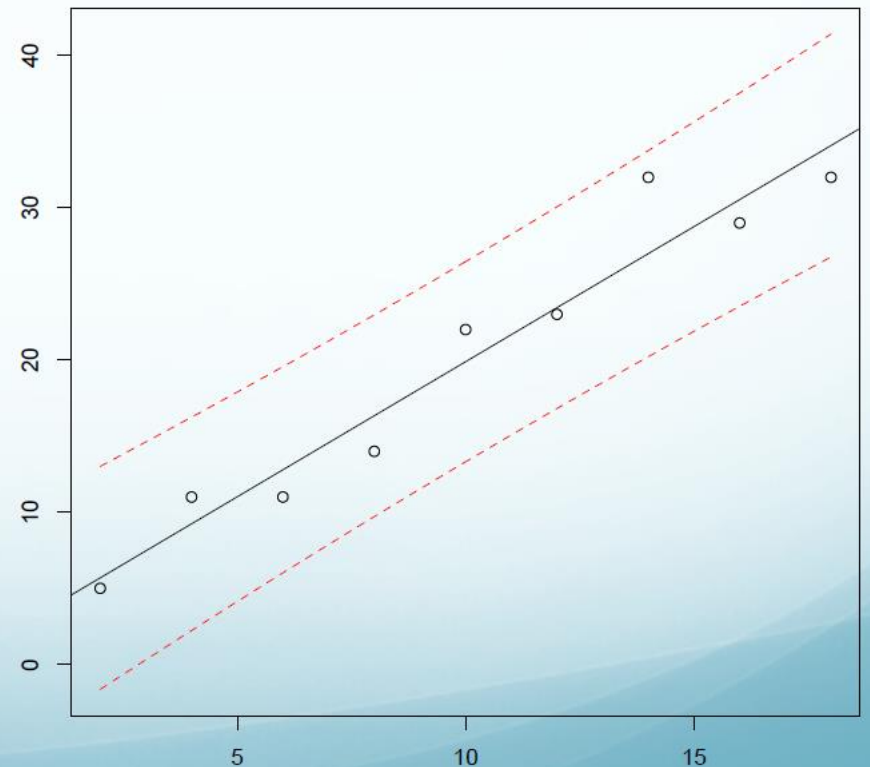
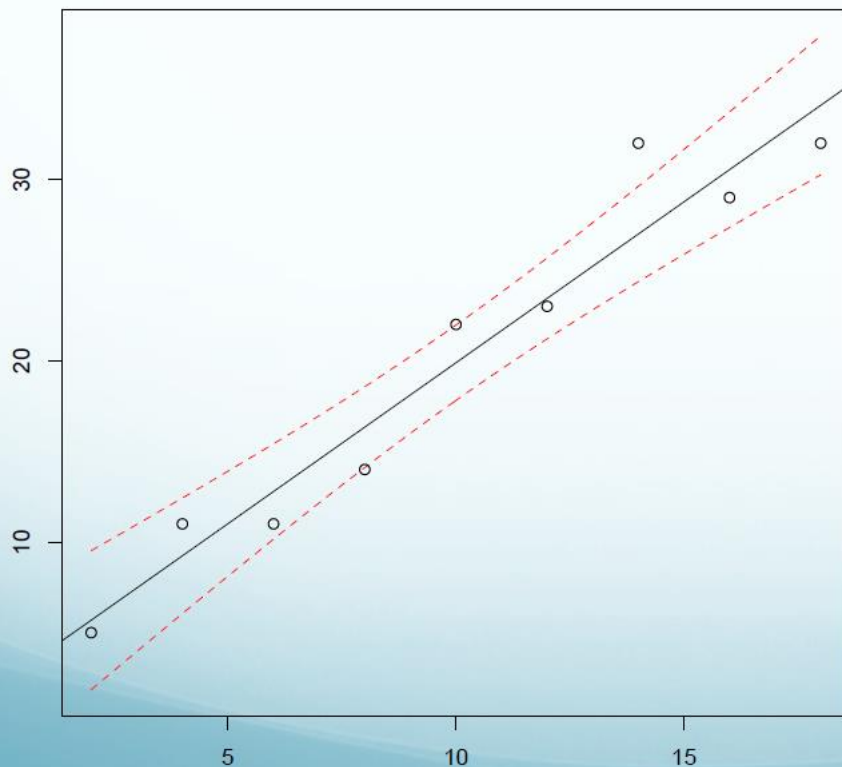
Aggregate Estimation

- Use field data to evaluate the variability in tissue measurements associated with repeat sampling
- Method 1: Use distribution of residuals from tissue isotope calibration relationship



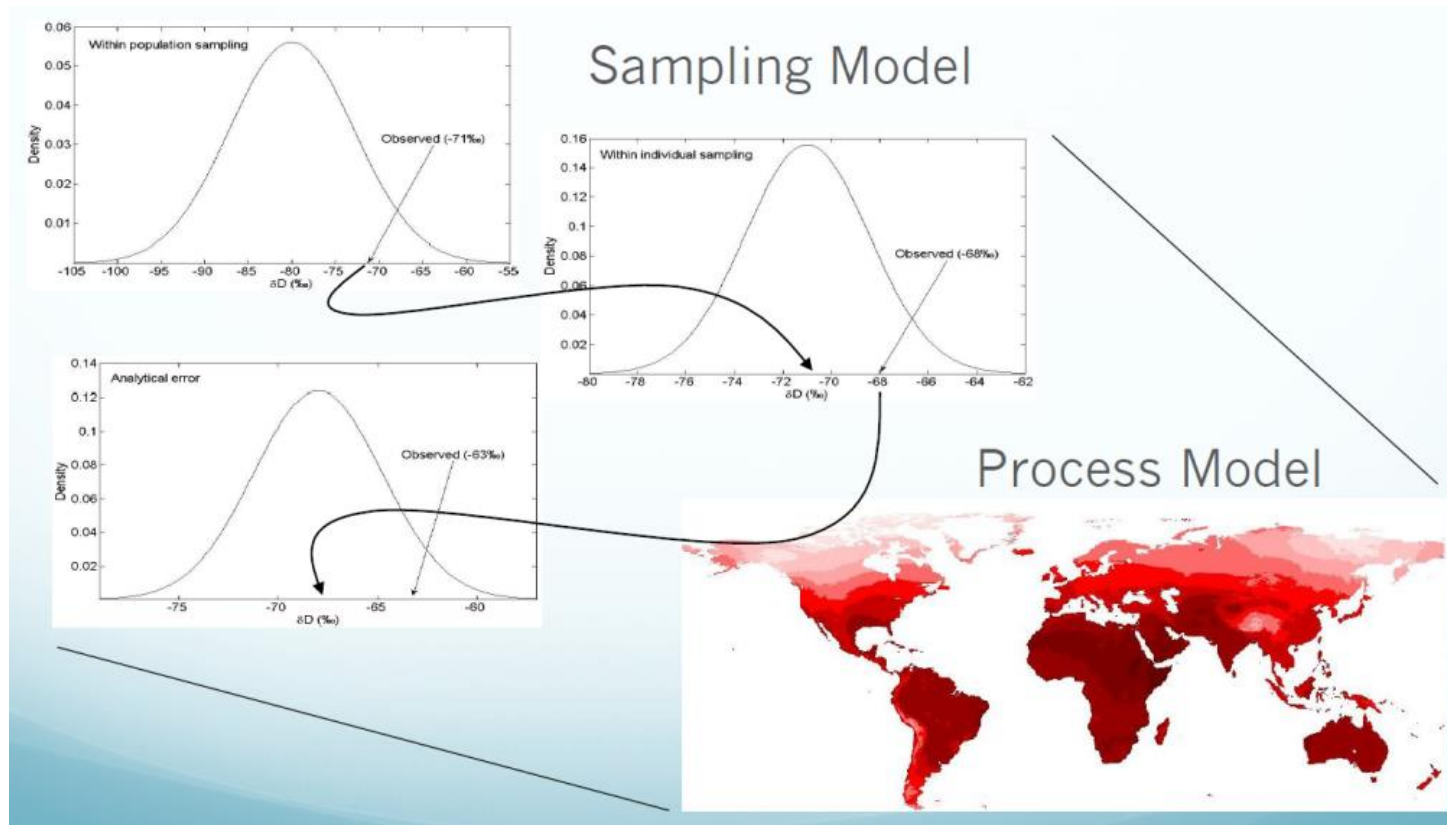
Aggregate Estimation

- ⊕ Method 2: Use prediction intervals for tissue isotope calibration relationship
- ⊕ Use sample statistics, not population statistics!



Hierarchical Estimation

- Build estimate from variance associated with individual model levels

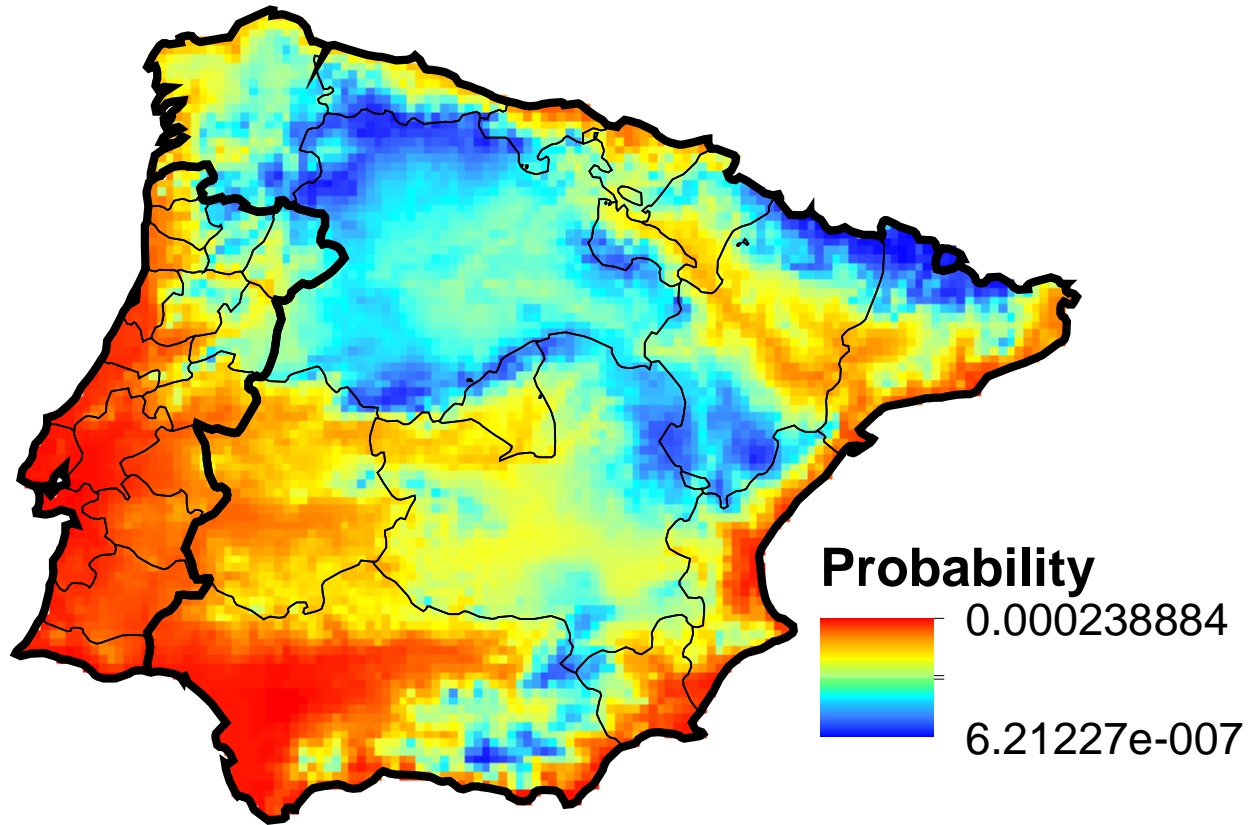


Simple Semi-Parametric Empirical Bayesian Assignment

$$P(\delta_s|A_i) = \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{\left(-\frac{(\delta_s - \mu_i)^2}{2\sigma_i^2}\right)}$$

- ⊕ Assumes normally distributed PDF for sample values at a given location
- ⊕ Aggregate or model-based estimate of within-site variance

Example Result



Incorporating Priors

$$P(A_i|B) = \frac{P(B|A_i)P(A_i)}{\sum P(B|A_j)P(A_j)}$$

- ⊕ In most cases we have some form of prior information
 - ⊕ Range maps
 - ⊕ Population density
 - ⊕ Band/recapture
- ⊕ Easy to impose any of these on our continuous analysis
IF we can represent the prior probability at each grid cell in our map area

Incorporating Priors

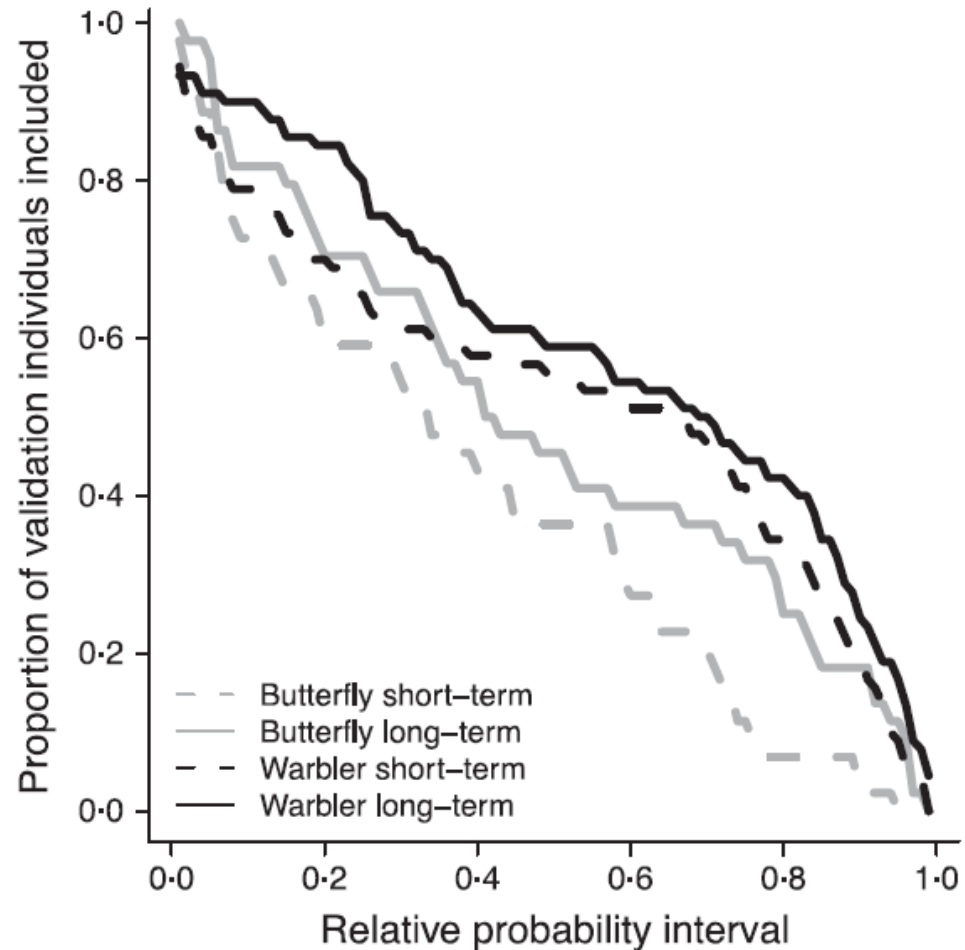


Interpreting Continuous Results

- ⊕ Often (usually) we want to aggregate results to answer specific ecological or management questions
- ⊕ Lots of flexibility to develop metrics suited to the question, but no single 'right' answer
- ⊕ Evaluating accuracy and precision
- ⊕ Comparing hypotheses (likelihood ratios)
- ⊕ Binary assignment (yes/no)
- ⊕ Working with multiple individuals

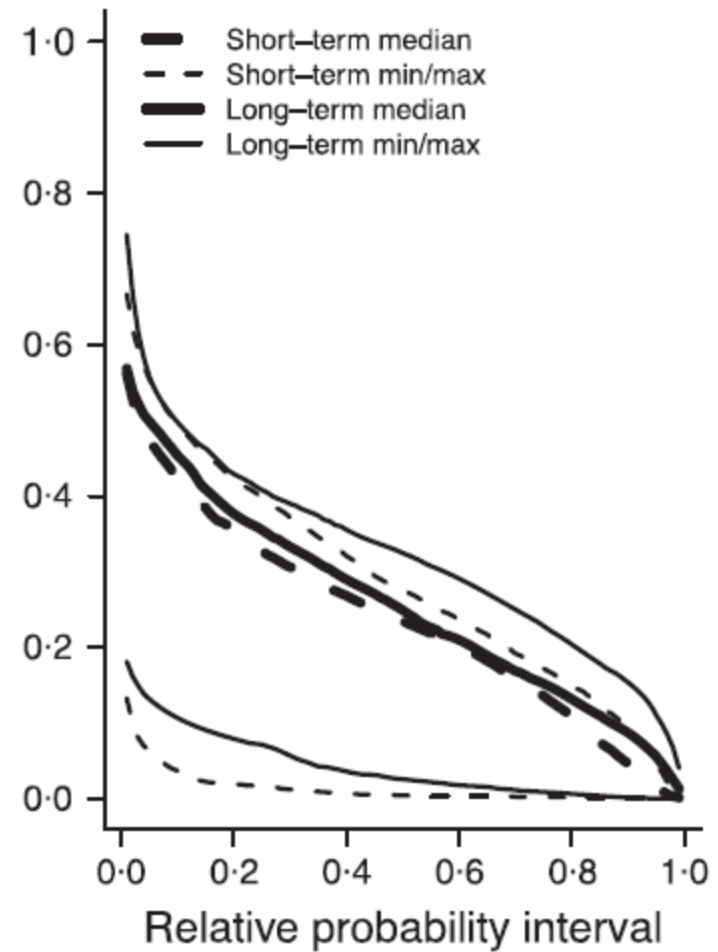
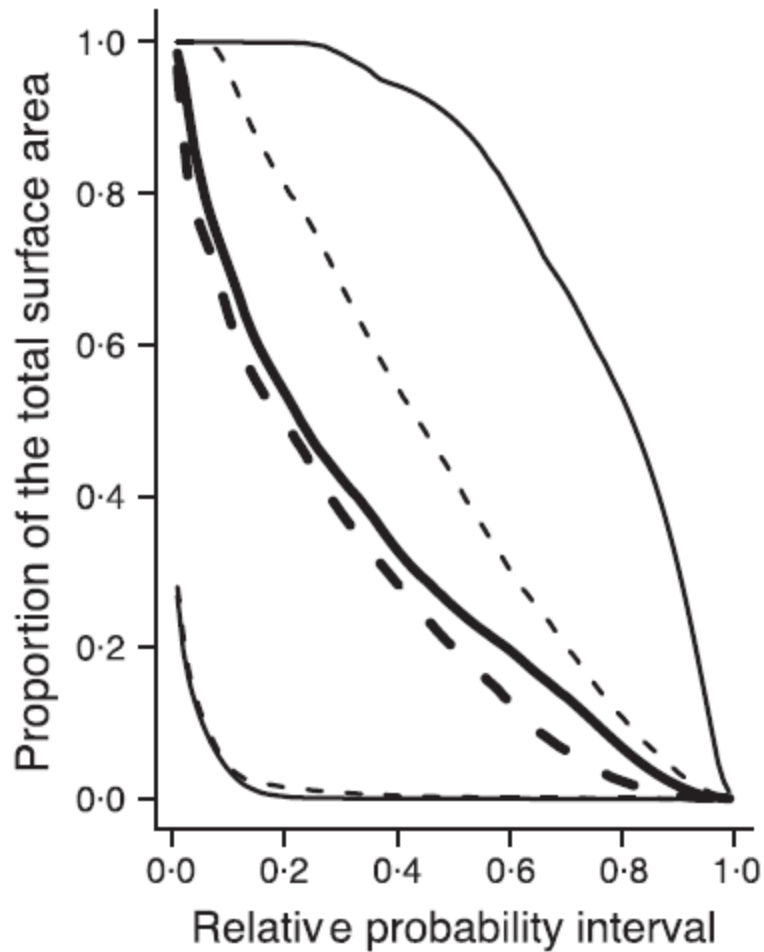
Known-origin Tests

Accuracy

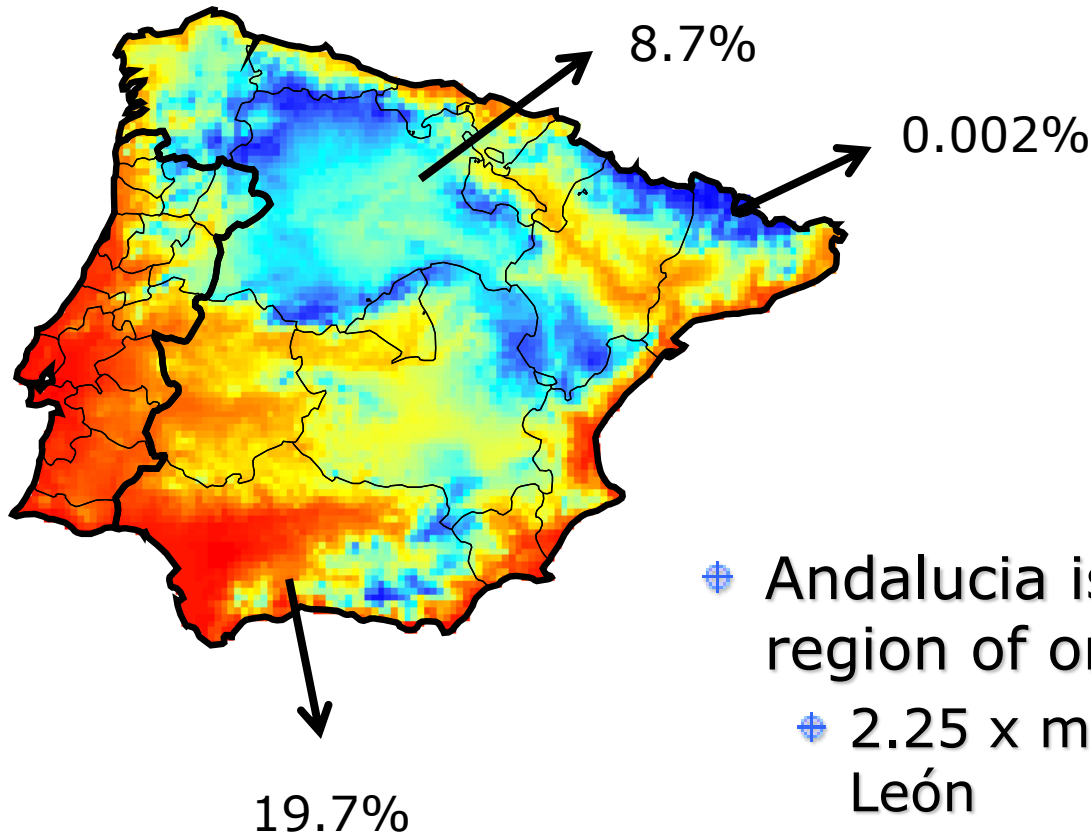


Known-origin Tests

⊕ Precision



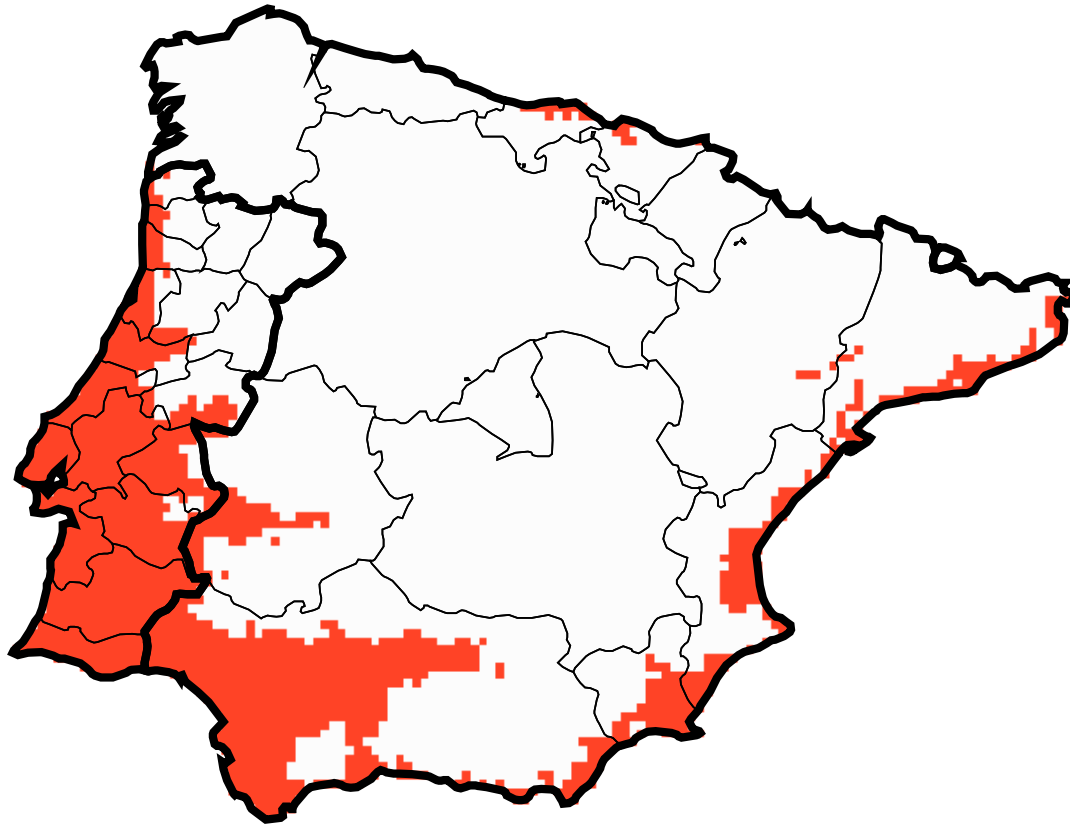
Comparing Hypotheses



- ⊕ Andalucía is the most likely region of origin
 - ⊕ 2.25 x more likely than Castilla y León
 - ⊕ 7,600 x more likely than Andorra

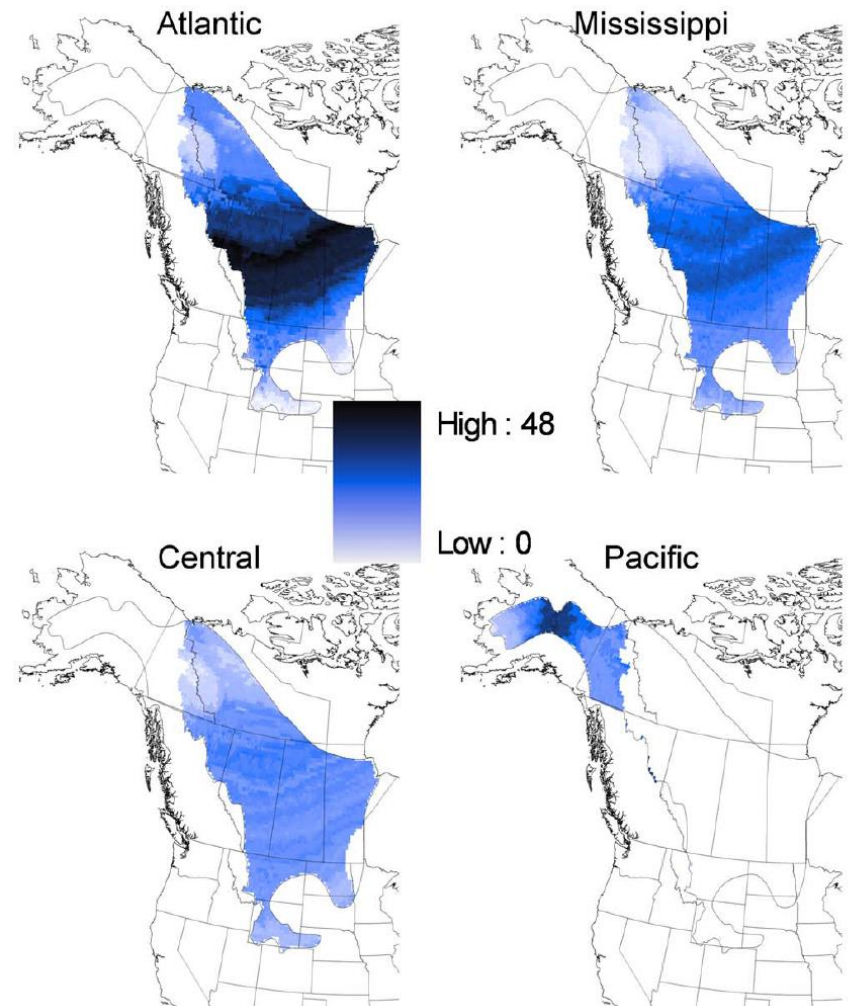
Binary Assignment

- Choose threshold, mask area of 'possible' origin



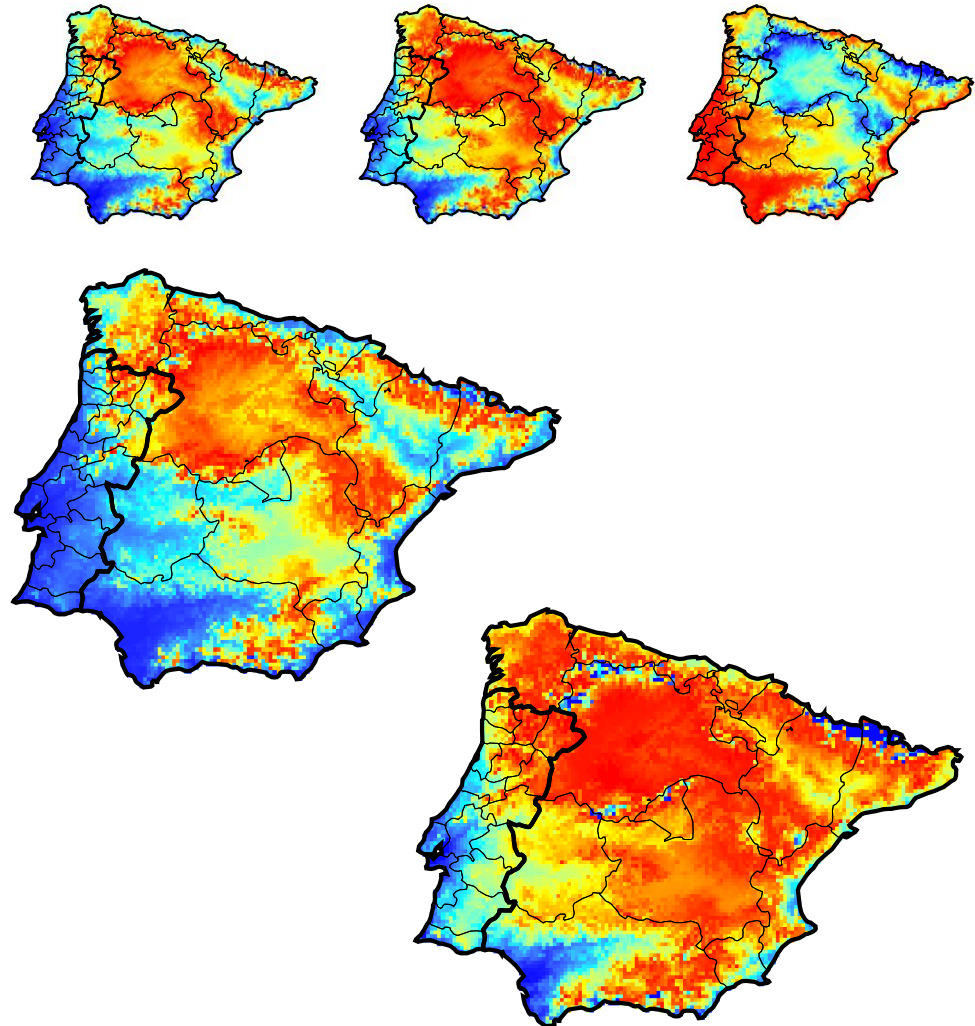
Multiple Individuals

- ⊕ Most studies (hopefully!) have >1 sample
- ⊕ How do we summarize information from individuals?
- ⊕ Binary assignment \rightarrow summation



Multiple Individuals

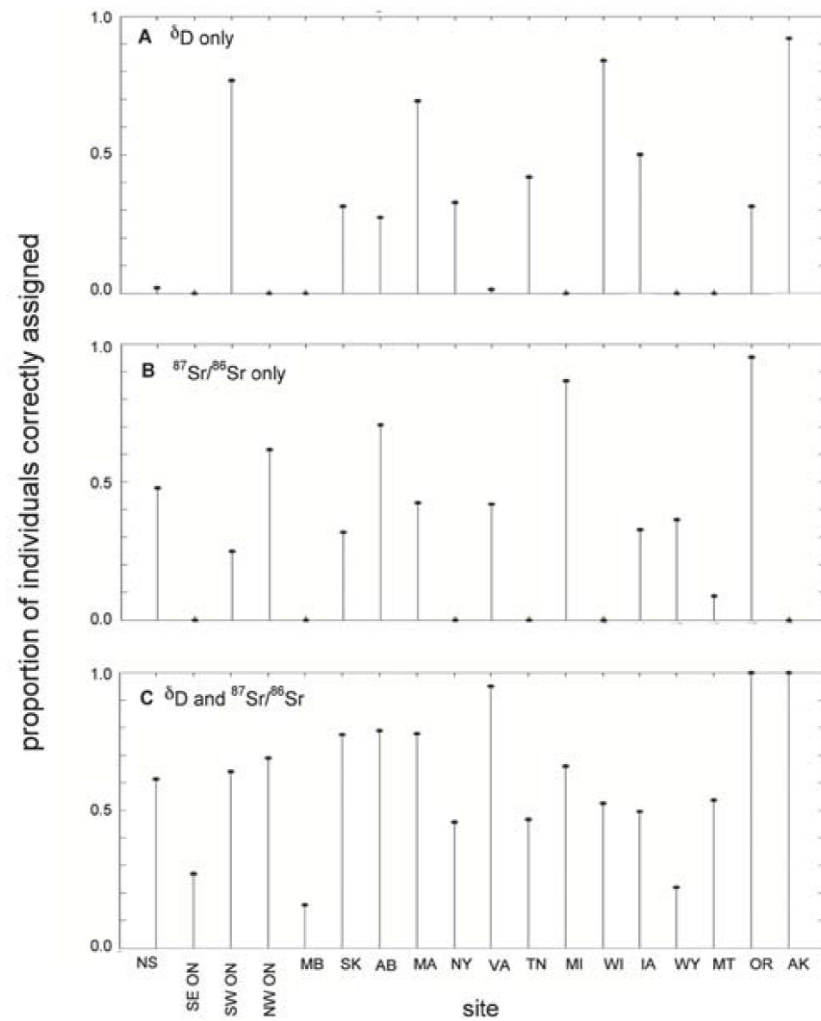
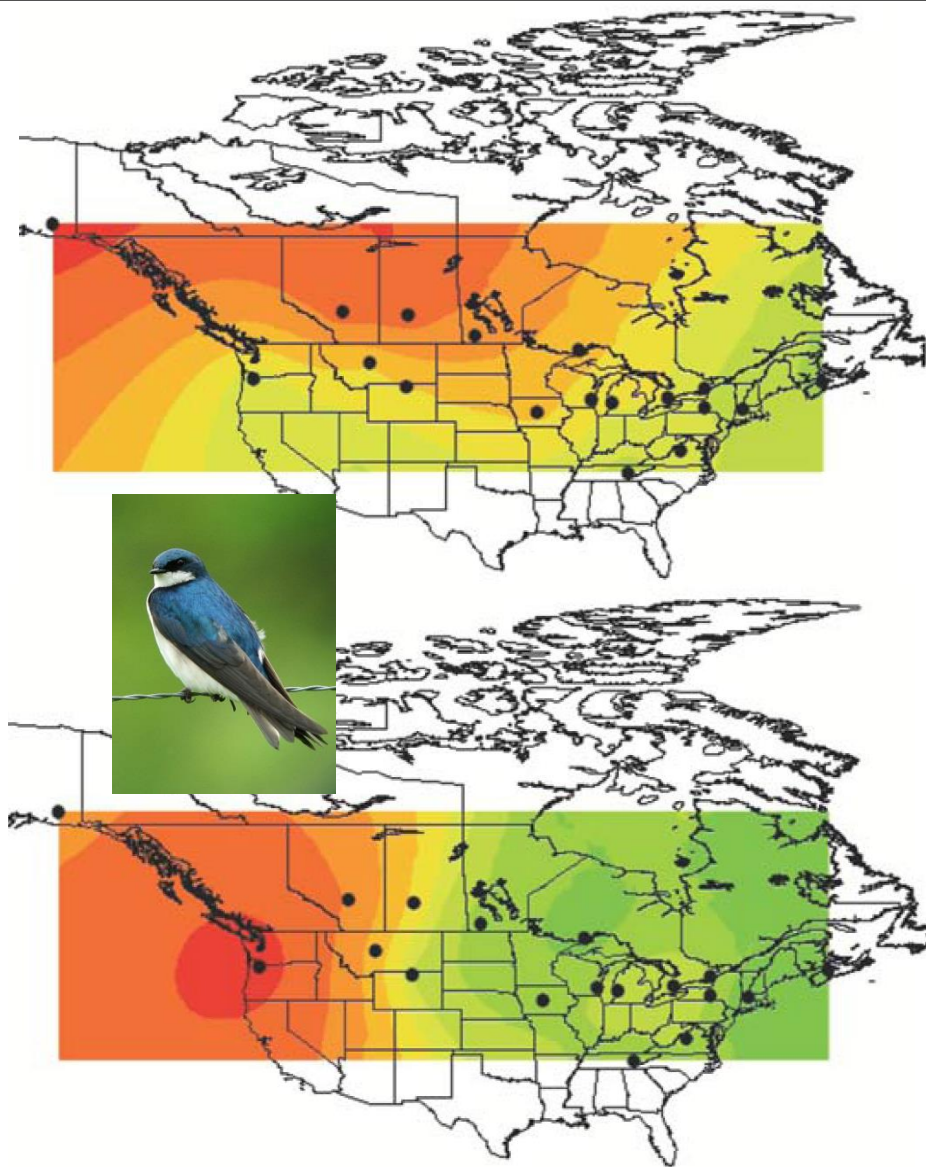
- ⊕ Joint probability
- ⊕ Probability that BOTH samples are from a location (intersection):
 - ⊕ $P(A \cap B) = P(A) \times P(B)$
- ⊕ Probability that ANY sample is from a location (union):
 - ⊕ $P(A \cup B) = P(A) + P(B) - P(A \cap B)$



Multiple Markers

- ⊕ Multiple markers (isotopes, elements, etc.) can increase precision of results
 - ⊕ Requires more data, more models, more assumptions!
 - ⊕ Not all marker systems are structured similarly or useful in the same way!
- ⊕ Two approaches:
 - ⊕ Assume independence, calculate joint conditional probability $P(B_1, B_2|A_i) = P(B_1|A_i) \times P(B_2|A_i)$
 - ⊕ Characterize the covariance structure of the joint spatial distribution of the markers

Multiple Markers



Multiple Markers

